RESEPI



System

System Accuracy	2 - 3 cm ⁽¹⁾
Precision	2 - 4 cm ⁽¹⁾
Precision (Io Noise Removal)	1.5 - 2.5 cm ⁽²⁾
Recommended AGL	Up to 100 m
Weight	1.2 kg
Dimensions	13.1 x 11.2 x 10.3 cm
Max Flight Time (DJI M350)	35 minutes
External Storage	256GB USB
System Computer	Quad Core 1GB RAM, 8GB eMMC
Operational Voltage Range	9-45V
Power Consumption	14.5 Watts

Software (PCMasterPro™)

Field Checks	Yes
Pre-Processing	Yes
Post-Processing	Yes, Supported
SLAM (Powered by Kudan)	Yes
Strip Alignment (Powered by BayesMap)	Yes
Additional Features	Coordinate System Transformation, Batch Processing, Noise Filtering, etc.

RESEPI™ Ultra LITE

RESEPI Ultra LITE Overview

Introducing the latest innovation from Inertial Labs, the lightest complete payload featuring both LiDAR and camera technology. Designed with the modern surveyor in mind, this solution offers unparalleled ease of use and versatility.

Key Features:

- Light Weight Design: Our lightest payload yet, ensuring ease of transport and deployment without compromising on performance.
- SnapFit Adapters: Experience seamless integration with various platforms (Freefly, WISPR, DJI, Sony, Mobile) through our quick plug-and-play SnapFit adapters, allowing for rapid dismounting and mounting.
- · Cost-Effective: As the most affordable and comprehensive solution we've released, it provides exceptional value without sacrificing quality.
- Precision and Accuracy: High data accuracy and precision has remained our priority and promise to our customers. This product has gone through metiluous cycles of testing and refining in proper time-stamping and calibration methods to make sure we bring unrivaled performance at the right value.
- Multi-Mode Operations: Versatile in application, it supports aerial scanning, pedestrian hand-held SLAM operations, and vehicle-mounted mobile mapping, making it an all-in-one solution for diverse surveying needs.

This product embodies Inertial Labs' commitment to innovation and excellence, providing surveyors and key-players in the 3D mapping space with a powerful tool that enhances efficiency and accuracy in their mapping projects.

Featuring the Hesai XT-32

Compact and light-weight, the RESEPI featuring Hesai's XT-32 LiDAR scanner is an all-around very attractive system, offering the benefits of best-in-class data accuracy, good detection range, high point density, and versatility.

Applications and Ideal Use Cases

The RESEPI Ultra LITE featuring Hesai's XT-32 LiDAR was strategically designed to accomodate the market needs for an all-in-one system that delivers accuracy and precision to 3D mapping applications. The RESEPI Ultra LITE has SnapFit adapters designed and released specifically to support common Freefly, WISPR, and DJI drones. This payload with it's embedded 5MP colorization camera and ultra-lightweight design is going to achieve maximum return for endurance missions in aerial mapping and low to mid-range altitudes. Given the compact nature of the system it is also perfect for SUAS integrators to adopt and bring inside to any platform with volume constraints where both LiDAR and a camera are the desired configuration. This RESEPI system will see its highest return on investment where customers are conscious of cost but still desiring to see a quality point cloud primarily in the applications of: utilities mapping (power lines), construction volumetrics, site surveying, precision agriculture, forestry, mining operations, and much more.

About Inertial Labs

Inertial Labs is at the forefront of developing and manufacturing position and orientation technologies for the commercial sector, government, defense, and aerospace. Inertial Labs' product catalog includes Inertial Measurement Units (IMU), Inertial Navigation Systems (INS), Motion Reference Units (MRU), and Wave Sensors (WS) along with RESEPI, our LiDAR scanning and mapping package. We supply solutions for land, sea, and air to exacting customers from some of the largest organizations in the world.

LiDAR

Laser Range Capabilities	80m @ 10% ref. (c9-24) 50m @ 10% ref. (c1-8, 25-32) 0.05 to 120m
Range Accuracy	+/- 1cm
FOV (Horizontal)	360°
FOV (Vertical)	31°
Scan Angle (Vertical)	-16° to 15°
Beam Divergence	0.021° (H), 0.047° (V) ⁽³⁾
Number of Laser	32
Number of Returns	2
Pulse Rate	640k/s (single return); 1280k/s (dual return)

Colorization Camera

Туре	CMOS Rolling Shutter
Resolution	5MP
Lens	Fixed Manual Focus
Max Trigger Rate	2 s
Field of View	HFOV = 70.8°, VFOV = 55.6°

 $^{\scriptsize (l)} Single$ Pass, 50m AGL, 5m/s, Nadir, Values Based on Inertial Labs Test Conditions.

 $^{\rm (2)}$ Single Pass, 50m AGL, 5m/s, Nadir, Single Noise Removal, Values Based on Inertial Labs Test Conditions.

⁽³⁾Varies by measurement range

⁽⁴⁾Dynamic accuracy is dependent on type of motion.

GPS-Aided INS

GPS-Aided Inertial Navigation System			
GNSS	NovAtel OEM7500		
Constellations	GPS, GLONASS, Galileo, BeiDou, QZSS, SBAS, L-Band		
Frequencies	L1, L1C, L2, L2C, B1, B2, E1, E5b		
Operation Modes	RTK and PPK		
INS Algorithm Type	Extended Kalman Filter		
Output Rates	Up to 200Hz (INS); Up to 2,000Hz (IMU)		
Pitch/Roll Accuracy	0.03° (RTK); 0.006° (PPK) ⁽⁴⁾		
Heading Accuracy	0.1° (RTK); 0.03 (PPK) ⁽⁴⁾		
Velocity Accuracy	<0.03m/s		
Position Accuracy	1cm + 1ppm (RTK); 0.5cm (PPK)		

Inertial Measurement Unit

IMU Type	Inertial Labs Kernel
Accelerometer	
Bias in-run stability (Allan Variance)	0.02 mg, lσ
Noise. Velocity Random Walk (VRW)	0.045 m/sec/√hr, 1σ
Scale Factor (STD, over temperature range)	100 ppm, 1σ
Gyroscope	
Bias in-run stability (Allan Variance)	2 deg/hr, 1σ
Noise. Angle Random Walk (ARW)	0.23 deg/√hr, 1σ
Scale Factor (STD, over temperature range)	600 ppm, lσ

